

# Intel® G35 Express Chipset

Thermal and Mechanical Design Guidelines

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— *For the Intel® 82G35 Graphics and Memory Controller Hub  
(GMCH)*

*August 2007*



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## *Revision History*

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Revision Number	Description	Date
-001	<ul style="list-style-type: none"><li>Initial release.</li></ul>	August 2007

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# 1 Introduction

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As the complexity of computer systems increases, so do power dissipation requirements. The additional power of next generation systems must be properly dissipated. Heat can be dissipated using improved system cooling, selective use of ducting, and/or passive heatsinks.

The objective of thermal management is to ensure that the temperatures of all components in a system are maintained within functional limits. The functional temperature limit is the range within which the electrical circuits can be expected to meet specified performance requirements. Operation outside the functional limit can degrade system performance, cause logic errors, or cause component and/or system damage. Temperatures exceeding the maximum operating limits may result in irreversible changes in the operating characteristics of the component.

This document is for the following device:

- Intel® G35 Express Chipset GMCH (82G35 GMCH)

This document presents the conditions and requirements to properly design a cooling solution for systems that implement the GMCH. Properly designed solutions provide adequate cooling to maintain the GMCH case temperature at or below thermal specifications. This is accomplished by providing a low local-ambient temperature, ensuring adequate local airflow, and minimizing the case to local-ambient thermal resistance. By maintaining the GMCH case temperature at or below those recommended in this document, a system designer can ensure the proper functionality, performance, and reliability of this component.

**Note:** Unless otherwise specified the information in this document applies to all configurations of the Intel® G35 Express Chipset. The Intel® G35 Express Chipset will be available with integrated graphics and associated SDVO and analog display ports. The Intel® G35 Express Chipset is a Graphics Memory Controller Hub (GMCH) targeted for use with the Intel® Core™2 Duo processor family and Intel® Core™2 Quad processor family in the LGA775 Land Grid Array Package and the Intel® ICH8 in desktop platforms.

**Note:** In this document the use of the term chipset refers to the combination of the GMCH and the Intel ICH8. For the ICH8 thermal details, refer to the *Intel® I/O Controller Hub 8 (ICH8) Thermal Design Guidelines*.



## 1.1 Terminology

Term	Description
FC-BGA	Flip Chip Ball Grid Array. A package type defined by a plastic substrate where a die is mounted using an underfill C4 (Controlled Collapse Chip Connection) attach style. The primary electrical interface is an array of solder balls attached to the substrate opposite the die. Note that the device arrives at the customer with solder balls attached.
Intel® ICH8	Intel® I/O Controller Hub 8. The chipset component that contains the primary PCI interface, LPC interface, USB, ATA, and/or other legacy functions.
GMCH	Graphic Memory Controller Hub. The chipset component that contains the processor and memory interface and integrated graphics core.
$T_A$	The local ambient air temperature at the component of interest. The ambient temperature should be measured just upstream of airflow for a passive heatsink or at the fan inlet for an active heatsink.
$T_C$	The case temperature of the GMCH component. The measurement is made at the geometric center of the die.
$T_{C-MAX}$	The maximum value of $T_C$ .
$T_{C-MIN}$	The minimum value of $T_C$ .
TDP	Thermal Design Power is specified as the maximum sustainable power to be dissipated by the GMCH. This is based on extrapolations in both hardware and software technology. Thermal solutions should be designed to TDP.
TIM	Thermal Interface Material: thermally conductive material installed between two surfaces to improve heat transfer and reduce interface contact resistance.
$\Psi_{CA}$	Case-to-ambient thermal solution characterization parameter (Psi). A measure of thermal solution performance using total package power. Defined as $(T_C - T_A) / \text{Total Package Power}$ . Heat source size should always be specified for $\Psi$ measurements.





## 1.2 Reference Documents

Document	Location
<i>Intel® G35 Express Chipset Datasheet</i>	<a href="http://www.intel.com/design/chipsets/datasheets/317607.htm">http://www.intel.com/design/chipsets/datasheets/317607.htm</a>
<i>Intel® I/O Controller Hub 8 (ICH8) Family Thermal Design Guidelines</i>	<a href="http://www.intel.com/design/chipsets/designex/313058.htm">http://www.intel.com/design/chipsets/designex/313058.htm</a>
<i>Intel® Core™2 Duo Processor and Intel® Pentium® Dual Core Processor Thermal and Mechanical Design Guidelines</i>	<a href="http://www.intel.com/design/processor/specupdt/313279.htm">http://www.intel.com/design/processor/specupdt/313279.htm</a>
<i>Intel® Core™2 Extreme Quad-Core Processor and Intel® Core™2 Quad Processor Thermal and Mechanical Design Guidelines</i>	<a href="http://www.intel.com/design/processor/designex/315594.htm">http://www.intel.com/design/processor/designex/315594.htm</a>
<i>Balanced Technology Extended (BTX) Interface Specification</i>	<a href="http://www.formfactors.org">http://www.formfactors.org</a>
<i>Various System Thermal Design Suggestions</i>	<a href="http://www.formfactors.org">http://www.formfactors.org</a>
<i>Various Chassis Thermal and Mechanical Design Suggestions</i>	<a href="http://www.formfactors.org">http://www.formfactors.org</a>

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## **2**      *Product Specifications*

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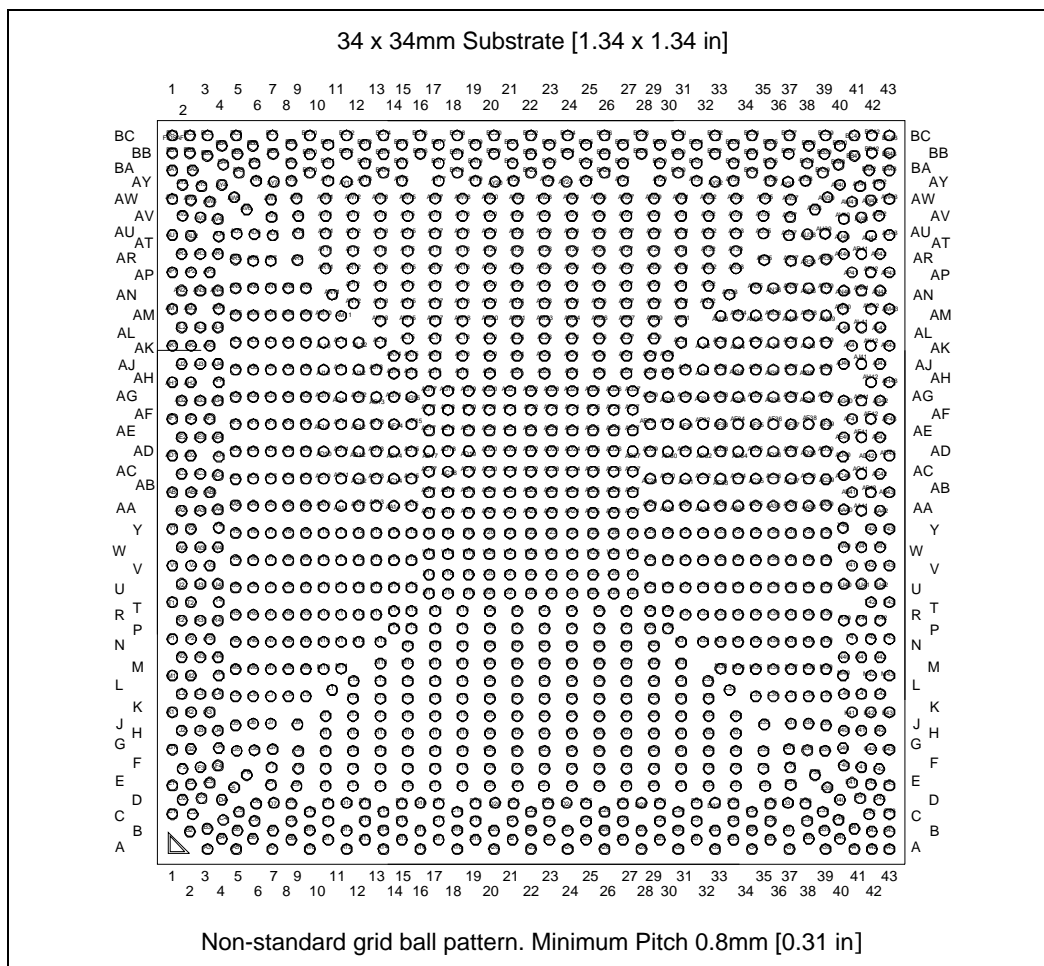
### **2.1**      **Package Description**

The GMCH is available in a 34 mm [1.34 in] x 34 mm [1.34 in] Flip Chip Ball Grid Array (FC-BGA) package with 1226 solder balls. The die size is currently 11.83 mm [0.466in] x 10.52 mm [0.414in] and is subject to change. A mechanical drawing of the package is shown in Figure 11.

#### **2.1.1**      **Non-Grid Array Package Ball Placement**

The GMCH package uses a “balls anywhere” concept. Minimum ball pitch is 0.8 mm [0.031 in], but ball ordering does not follow a 0.8-mm grid. Board designers should ensure correct ball placement when designing for the non-grid array pattern. For exact ball locations relative to the package, contact your Intel Field Sales Representative.

Figure 1. GMCH Non-Grid Array



## 2.2 Package Loading Specifications

Table 1 provides static load specifications for the package. This mechanical maximum load limit should not be exceeded during heatsink assembly, shipping conditions, or standard use condition. Also, any mechanical system or component testing should not exceed the maximum limit. The package substrate should not be used as a mechanical reference or load-bearing surface for the thermal and mechanical solution.

Table 1. Package Loading Specifications

Parameter	Maximum	Notes
Static	15 lbf	1,2,3

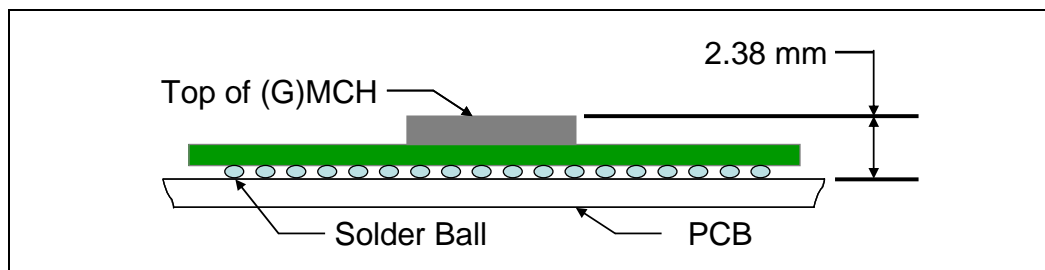
### NOTES:

- These specifications apply to uniform compressive loading in a direction normal to the package.
- This is the maximum force that can be applied by a heatsink retention clip. The clip must also provide the minimum specified load on the package.
- These specifications are based on limited testing for design characterization. Loading limits are for the package only.



To ensure the package static load limit is not exceeded, the designer should understand the post reflow package height. The following figure shows the nominal post-reflow package height assumed for calculation of a heatsink clip preload of the reference design. Refer to the package drawing in Appendix B to perform a detailed analysis.

**Figure 2. Nominal Package Height**



## 2.3 Thermal Specifications

To ensure proper operation and reliability of the GMCH, the temperature must be at or below the maximum case temperature specified in Table 2 when operating at TDP. System and component level thermal enhancements are required to dissipate the heat generated and maintain the GMCH within specifications. Chapter 0 provides the thermal metrology guidelines for case temperature measurements.

The GMCH should also operate above the minimum case temperature specification listed in Table 2.

## 2.4 Thermal Design Power (TDP)

### 2.4.1 Definition

Thermal design power (TDP) is the estimated power dissipation of the GMCH based on normal operating conditions including  $V_{CC}$  and  $T_{C-MAX}$  while executing real worst-case power intensive applications. This value is based on expected worst-case data traffic patterns and usage of the chipset and does not represent a specific software application. TDP attempts to account for expected increases in power due to variation in GMCH current consumption due to silicon process variation, processor speed, DRAM capacitive bus loading and temperature. However, since these variations are subject to change, the TDP cannot guarantee that all applications will not exceed the TDP value.

The system designer must design a thermal solution for the GMCH such that it maintains  $T_C$  below  $T_{C-MAX}$  for a sustained power level equal to TDP. Please note that the  $T_{C-MAX}$  specification is a requirement for a sustained power level equal to TDP, and that the case temperature must be maintained at temperatures less than  $T_{C-MAX}$  when operating at power levels less than TDP. This temperature compliance is to ensure component reliability over its useful life. The TDP value can be used for thermal design if the thermal protection mechanisms are enabled. The GMCH incorporate a hardware-based fail-safe mechanism to keep the product temperature in specification in the event of unusually strenuous usage above the TDP power.



## 2.4.2 Methodology

### 2.4.2.1 Pre-Silicon

To determine TDP for pre-silicon products in development, it is necessary to make estimates based on analytical models. These models rely on knowledge of the past GMCH power dissipation behavior along with knowledge of planned architectural and process changes that may affect TDP. Knowledge of applications available today and their ability to stress various aspects of the GMCH is also included in the model. The projection for TDP assumes GMCH operation at  $T_{C-MAX}$ . The TDP estimate also accounts for normal manufacturing process variation.

### 2.4.2.2 Post-Silicon

Once the product silicon is available, post-silicon validation is performed to assess the validity of pre-silicon projections. Testing is performed on both commercially available and synthetic high power applications and power data is compared to pre-silicon estimates. Post-silicon validation may result in a small adjustment to pre-silicon TDP estimates.

## 2.4.3 Specifications

The data in Table 2 is based on post-silicon power measurements of the GMCH. The system configuration is: two (2) DIMMs per channel, DDR2, FSB operating at the top speed allowed by the chipset with a processor operating at that system bus speed. FC-BGA packages have poor heat transfer capability into the board and have minimal thermal capability without thermal solutions. Intel requires that system designers plan for an attached heatsink when using the GMCH.

**Table 2. Thermal Specifications**

Component	System Bus Speed	Memory Frequency	$T_{C-MIN}$	$T_{C-MAX}$	Max Idle Power	TDP Value
Intel® 82G35 GMCH	1333 MHz	800 MHz	0 °C	97°C	11 W	28 W

**NOTES:**

1. Thermal specifications assume an attached heatsink is present.
2. Max Idle Power is the worst case idle power in system booted to Windows\* with no background applications running.
3. When an external graphics card is installed in a system with the Intel® G35 Express Chipset, the TDP for this part will drop to approximately 19 W. The GMCH will detect the presence of the graphics card and disable the on-board graphics resulting in the lower GMCH TDP.

### 2.4.4 $T_{CONTROL}$ Limit

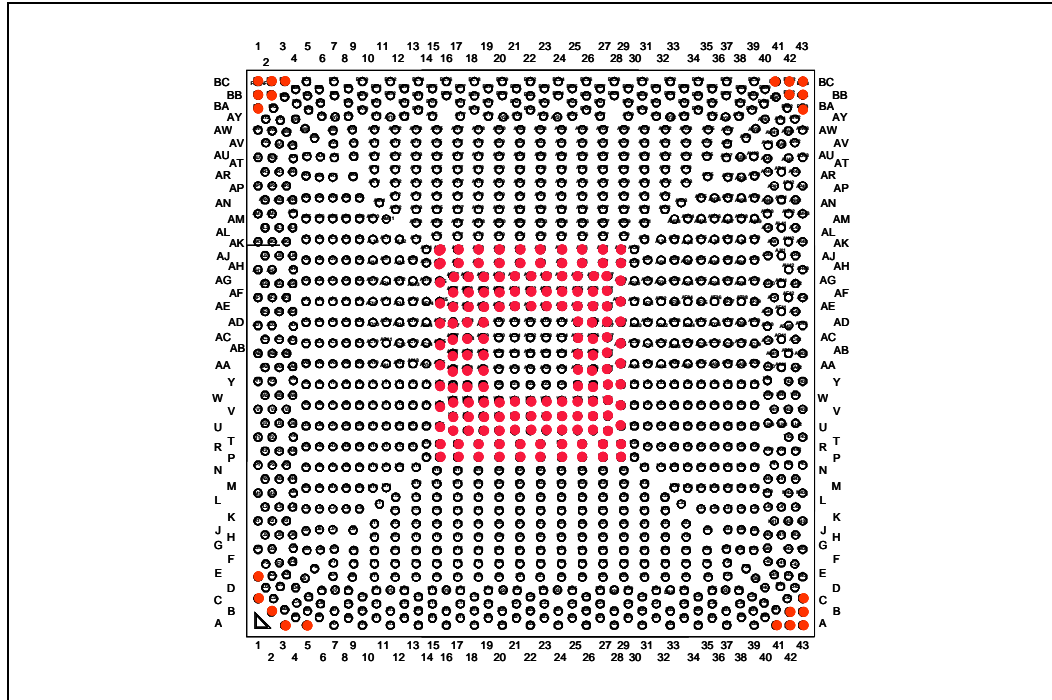
Intel® Quiet System Technology (Intel® QST) monitors an embedded thermal sensor. The maximum operating limit when monitoring this thermal sensor is  $T_{CONTROL}$ . For the GMCH this value has been defined as 95 °C. This value should be programmed into the appropriate fields of Intel QST as the maximum sensor temperature for operation of the Intel 82G35 GMCH.



## 2.5 Non-Critical to Function Solder Balls

Intel has defined selected solder joints of the GMCH as non-critical to function (NCTF) when evaluating package solder joints post environmental testing. The GMCH signals at NCTF locations are typically redundant ground or non-critical reserved, so the loss of the solder joint continuity at end of life conditions will not affect the overall product functionality. Figure 3 identifies the NCTF solder joints of the GMCH package.

Figure 3. Non-Critical to Function Solder Balls



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## 3 Thermal Metrology

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The system designer must measure temperatures in order to accurately determine the thermal performance of the system. Intel has established guidelines for proper techniques of measuring GMCH component case temperatures.

### 3.1 Case Temperature Measurements

To ensure functionality and reliability of the GMCH the  $T_C$  must be maintained at or below the maximum temperature listed in Table 2. The surface temperature measured at the geometric center of the die corresponds to  $T_C$ . Measuring  $T_C$  requires special care to ensure an accurate temperature reading.

Temperature differences between the temperature of a surface and the surrounding local ambient air can introduce error in the measurements. The measurement errors could be due to a poor thermal contact between the thermocouple bead and the surface of the package, heat loss by radiation and/or convection, conduction through thermocouple leads, or contact between the thermocouple cement and the heatsink base (if a heatsink is used). To minimize these measurement errors a thermocouple attach with a zero-degree methodology is recommended.

#### 3.1.1 Thermocouple Attach Methodology

1. Mill a 3.3 mm [0.13 in] diameter hole centered on bottom of the heatsink base. The milled hole should be approximately 1.5 mm [0.06 in] deep.
2. Mill a 1.3 mm [0.05 in] wide slot, 0.5 mm [0.02 in] deep, from the centered hole to one edge of the heatsink. The slot should be in the direction parallel to the heatsink fins (see Figure 5).
3. Attach thermal interface material (TIM) to the bottom of the heatsink base.
4. Cut out portions of the TIM to make room for the thermocouple wire and bead. The cutouts should match the slot and hole milled into the heatsink base.
5. Attach a 36 gauge or smaller K-type thermocouple bead to the center of the top surface of the die using cement with high thermal conductivity. During this step, make sure no contact is present between the thermocouple cement and the heatsink base because any contact will affect the thermocouple reading. **It is critical that the thermocouple bead makes contact with the die** (see Figure 4).
6. Attach heatsink assembly to the GMCH, and route thermocouple wires out through the milled slot.

Figure 4. 0° Angle Attach Methodology (top view, not to scale)

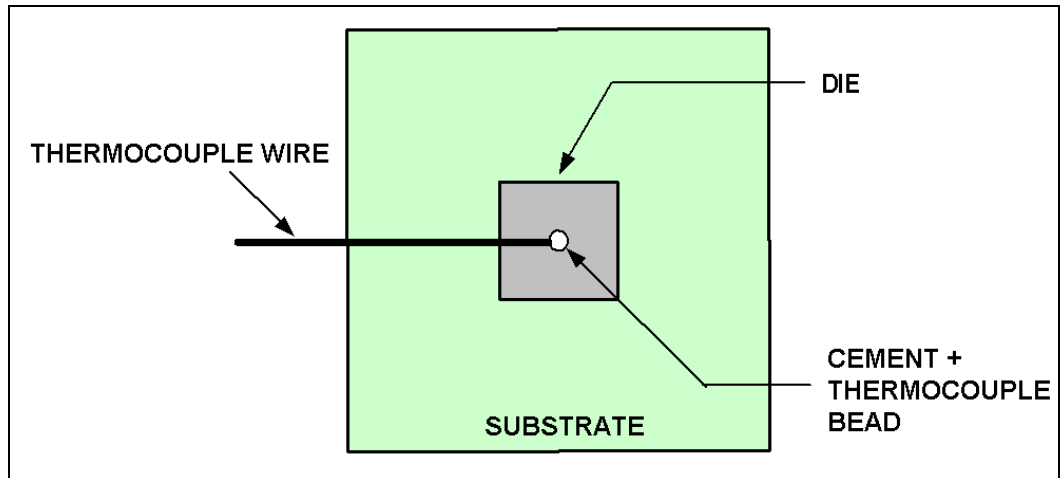
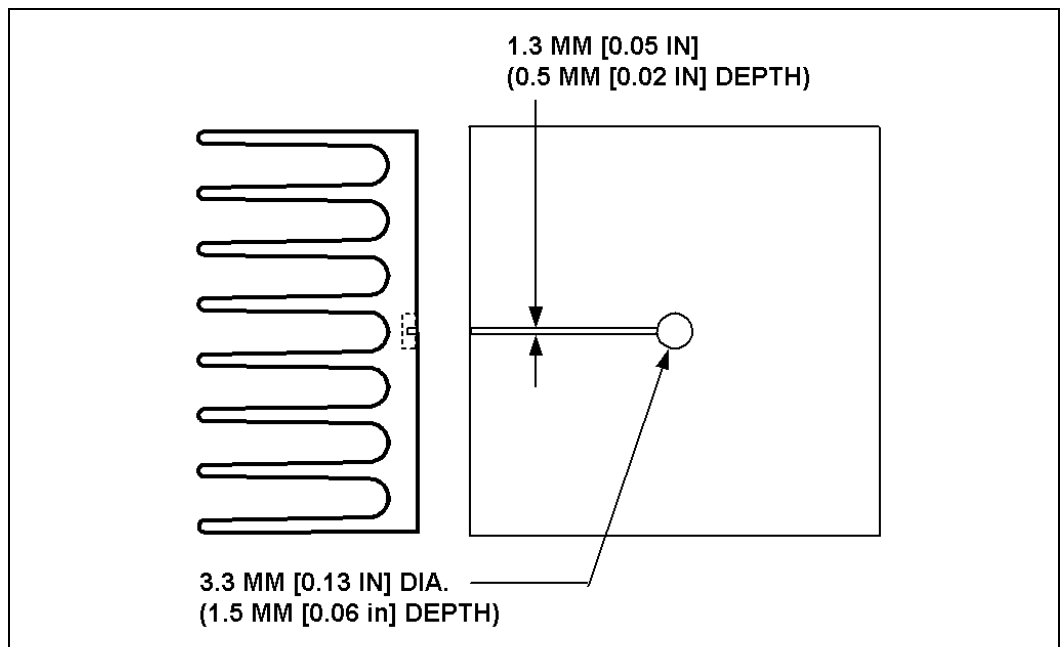


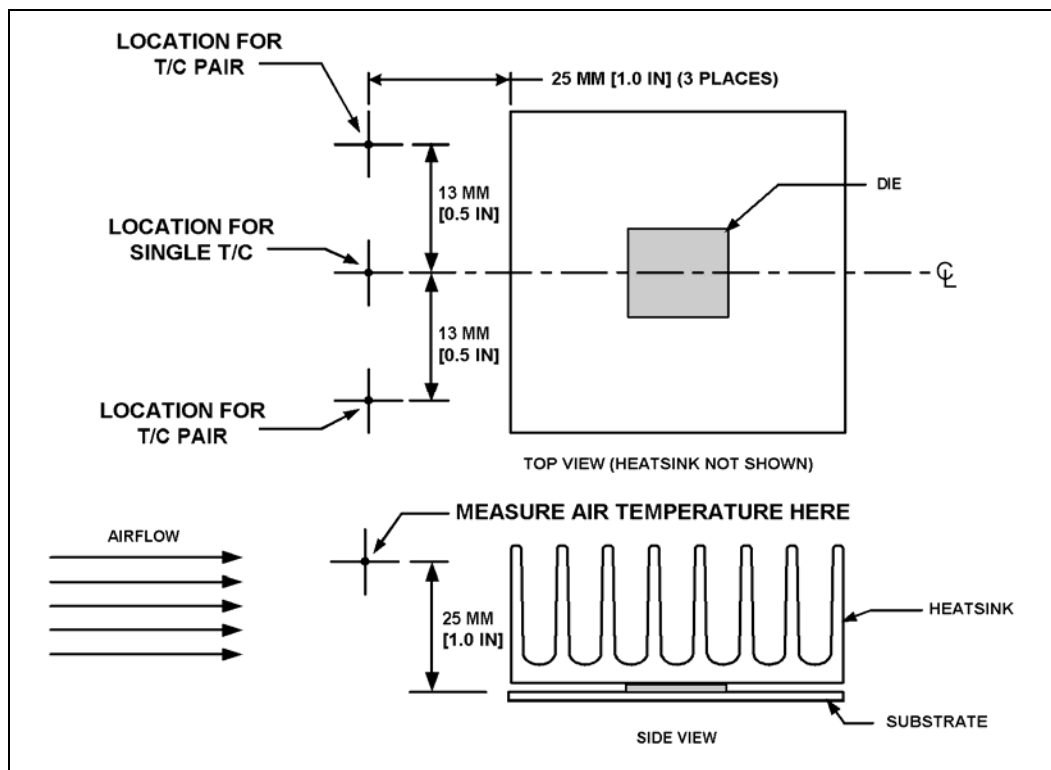
Figure 5. 0° Angle Attach Heatsink Modifications (generic heatsink side and bottom view shown, not to scale)



### 3.2 Airflow Characterization

Figure 6 shows the recommended location for air temperature measurements measured relative to the component. For a more accurate measurement of the average approach air temperature, Intel recommends averaging temperatures recorded from two thermocouples spaced about 25 mm [1.0 in] apart. Locations for both a single thermocouple and a pair of thermocouples are presented.

**Figure 6. Airflow and Temperature Measurement Locations**



Airflow velocity can be measured using sensors that combine air velocity and temperature measurements. Typical airflow sensor technology may include hot wire anemometers. Figure 6 provides guidance for airflow velocity measurement locations which should be the same as used for temperature measurement. These locations are for a typical JEDEC test setup and may not be compatible with chassis layouts due to the proximity of the processor to the GMCH. The user may have to adjust the locations for a specific chassis. Be aware that sensors may need to be aligned perpendicular to the airflow velocity vector or an inaccurate measurement may result. Measurements should be taken with the chassis fully sealed in its operational configuration to achieve a representative airflow profile within the chassis.





## 4 Reference Thermal Solution

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The design strategy for the reference component thermal solution for the Intel® G35 Express Chipset in ATX platforms reuses the ramp retainer, extrusion design and anchors from the Intel® 945G Express Chipset thermal solution. The thermal interface material and a wire preload clip are being redesigned to meet the Intel G35 Express Chipset thermal requirements.

The Balanced Technology Extended (BTX) reference design for the Intel G35 Express Chipset includes a new extrusion, clip with higher preload and a new thermal interface material. A slightly larger motherboard keep out zone than used by the Intel 945G Express Chipset thermal solution has been defined, see Figure 13.

This chapter provides detailed information on operating environment assumptions, heatsink manufacturing, and mechanical reliability requirements for the GMCH.

### 4.1 Operating Environment

The operating environment of the GMCH will differ depending on system configuration and motherboard layout. This section defines operating environment boundary conditions that are typical for ATX and Balanced Technology Extended (BTX) form factors. The system designer should perform analysis on platform operating environment to assess impact to thermal solution selection.

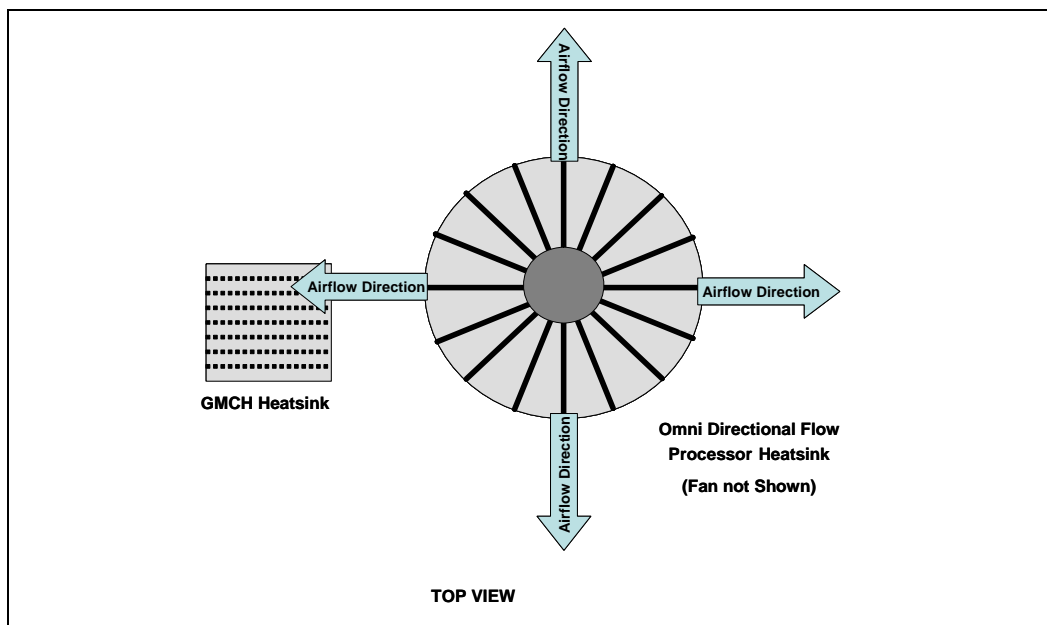
#### 4.1.1 ATX Form Factor Operating Environment

In ATX platforms, an airflow speed of 0.76 m/s [150 lfm] is assumed be present 25 mm [1 in] in front of the heatsink air inlet side of the attached reference thermal solution. The local ambient air temperature,  $T_A$ , at the GMCH heatsink in an ATX platform is assumed to be 47 °C. The system integrator should note that board layout may be such that there will not be 25 mm [1in] between the processor heatsink and the GMCH. The potential for increased airflow speeds may be realized by ensuring that airflow from the processor heatsink fan exhausts in the direction of the GMCH heatsink. This can be achieved by using a heatsink providing omni directional airflow, such as a radial fin or "X" pattern heatsink. Such heatsink can deliver airflow to both the GMCH and other areas like the voltage regulator, as shown in Figure 7. In addition, GMCH board placement should ensure that the GMCH heatsink is within the air exhaust area of the processor heatsink.

**Note that heatsink orientation alone does not ensure that 0.76 m/s [150 lfm] airflow speed will be achieved.** The system integrator should use analytical or experimental means to determine whether a system design provides adequate airflow speed for a particular GMCH heatsink.

The thermal designer must carefully select the location to measure airflow to get a representative sampling. ATX platforms need to be designed for the worst-case thermal environment, typically assumed to be 35 °C ambient temperature external to the system.

Figure 7. Processor Heatsink Orientation to Provide Airflow to GMCH Heatsink on an ATX Platform



Other methods exist for providing airflow to the GMCH heatsink, including the use of system fans and/or ducting, or the use of an attached fan (active heatsink).

#### 4.1.2 Balanced Technology Extended (BTX) Form Factor Operating Environment

This section provides operating environment conditions based on what has been exhibited on the Intel micro-BTX reference design. On a BTX platform, the GMCH obtains in-line airflow directly from the processor thermal module. Since the processor thermal module provides lower inlet temperature airflow to the processor, reduced inlet ambient temperatures are also often seen at the GMCH as compared to ATX. An example of how airflow is delivered to the GMCH on a BTX platform is shown in Figure 8.

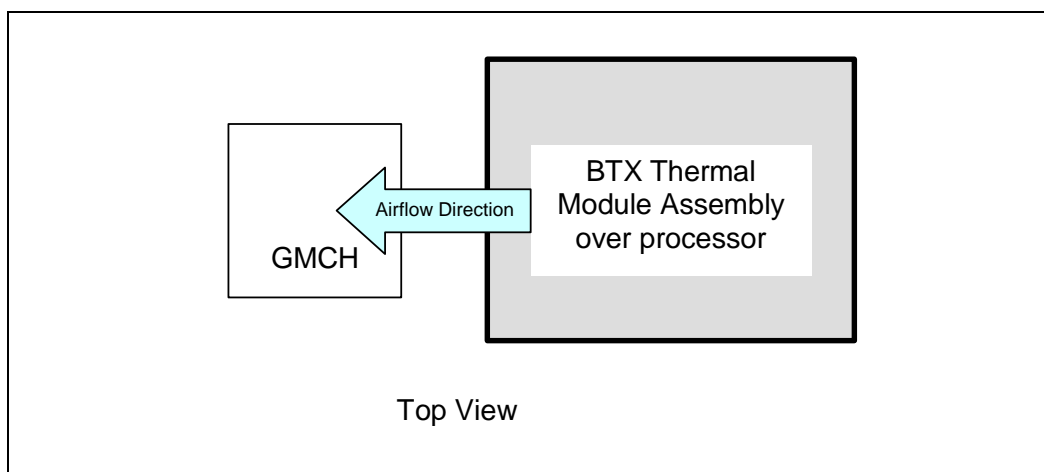
The local ambient air temperature,  $T_A$ , at the GMCH heatsink in the Intel micro-BTX reference design is predicted to be  $\sim 45^\circ\text{C}$ . The thermal designer must carefully select the location to measure airflow to get a representative sampling. These environmental assumptions are based on a  $35^\circ\text{C}$  system external temperature measured at sea level.

**Note:** The local ambient air temperature is based on the power for a 2005 platform, processor with a TDP up to 130 W.

**Note:** The risk of the solder ball fracture can be minimized with good chassis structure design on a BTX platform, refer to the *Balanced Technology Extended (BTX) Chassis Design Guide* (or *Balanced Technology Extended (BTX) System Design Guide*) for detailed chassis mechanical design.



**Figure 8. Processor Heatsink Orientation to Provide Airflow to GMCH Heatsink on a Balanced Technology Extended (BTX) Platform**



## 4.2 Reference Design Mechanical Envelope

The motherboard component keep-out restrictions for the GMCH for an ATX platform are included in Appendix B, Figure 12. The motherboard component keep-out restrictions for the GMCH on a BTX platform are included in Appendix B, Figure 13.

## 4.3 Thermal Solution Assembly

The reference thermal solution for the GMCH for an ATX chassis is shown in Figure 9 and is an aluminum extruded heatsink that uses two ramp retainers, a wire preload clip, and four motherboard anchors. Refer to Appendix B for the mechanical drawings. The heatsink is attached to the motherboard by assembling the anchors into the board, placing the heatsink over the GMCH and anchors at each of the corners, and securing the plastic ramp retainers through the anchor loops before snapping each retainer into the fin gap. The wire preload clip should be left loose in the extrusion during the wave solder process. The assembly is then sent through the wave process. Post wave, the wire preload clip is assembled using the hooks on each of the ramp retainers. The clip provides the mechanical preload to the package. The mechanical preload is necessary to provide both sufficient pressure to minimize thermal contact resistance and to improve solder ball joint reliability. The mechanical stiffness and orientation of the extruded heatsink also provides protection to reduce solder ball joint reliability. A thermal interface material (Honeywell\* PCM45F) is pre-applied to the heatsink bottom over an area which contacts the package die.

**Note:** The ATX design is similar in appearance to the Intel® 945G Express Chipset thermal solution, but two critical items have been changed.

- A higher performance TIM
- A clip with a higher preload to meet the TIM preload requirements.

The combination of the two new items provides the performance increase to meet the GMCH thermal requirements.

The reference thermal solution for the GMCH in a BTX chassis is shown in Figure 10. The heatsink is aluminum extruded and uses a Z-clip for attach. The clip is secured to the system motherboard via two solder down anchors around the GMCH. The clip helps to provide a mechanical preload to the package via the heatsink. A thermal interface material (Honeywell\* PCM45F) is pre-applied to the heatsink bottom over an area in contact with the package die.

**Note:** To minimize solder ball joint reliability risk, the BTX Z-clip heatsink is intended to be used with the Support Retention Mechanism (SRM) described in the *Balanced Technology Extended (BTX) Interface Specification*. For additional information on designing the BTX chassis to minimize solder ball joint reliability, refer to the *Balanced Technology Extended (BTX) Chassis Design Guide*.

**Figure 9. ATX GMCH Heatsink - Installed on Board**

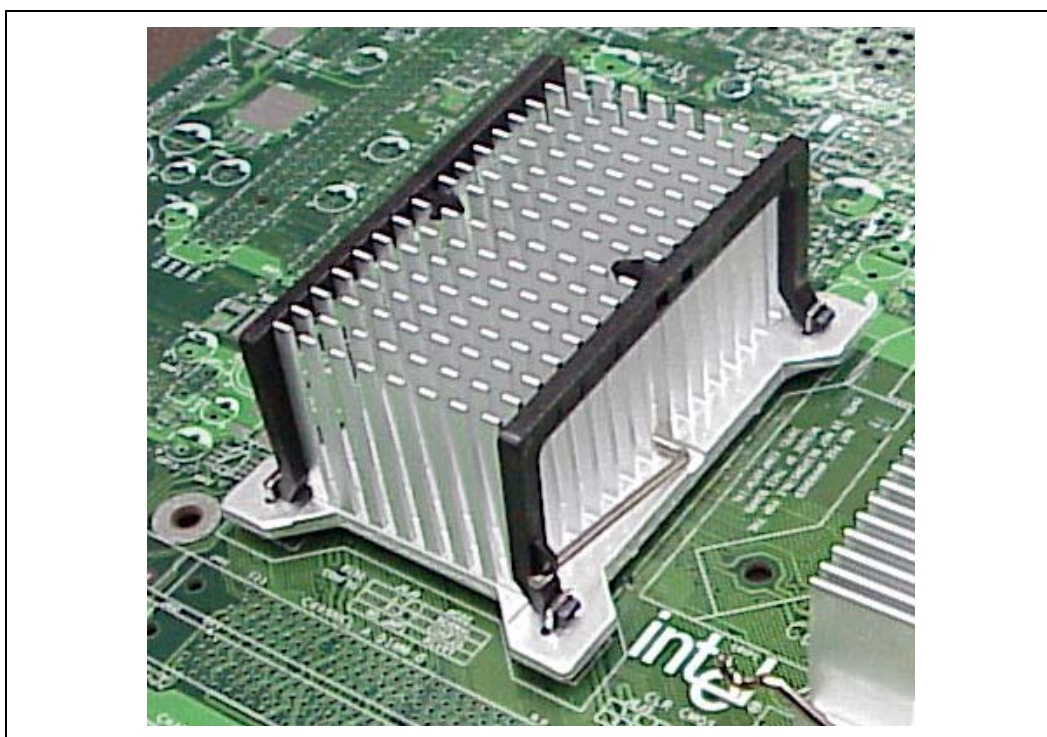
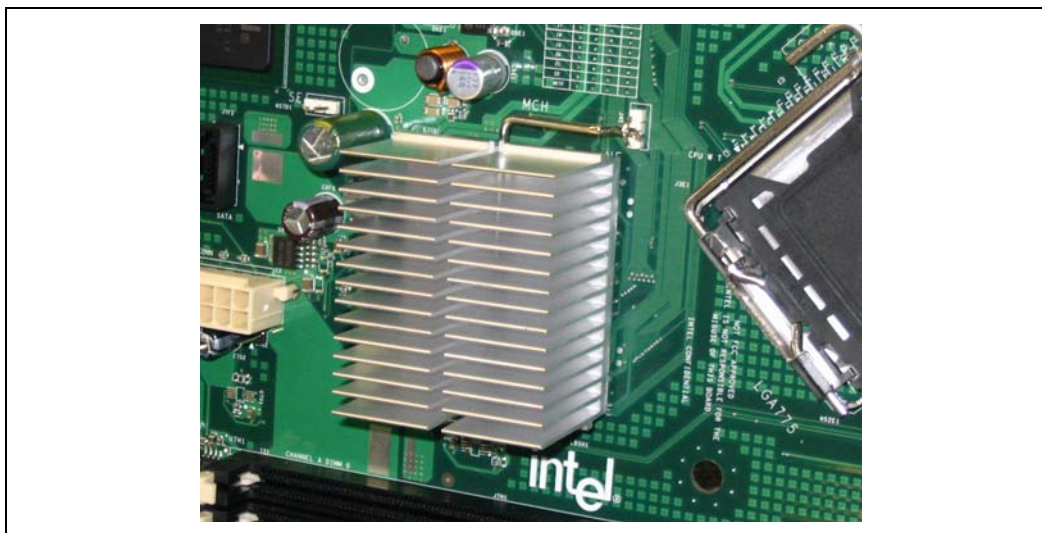




Figure 10. Balanced Technology Extended (BTX) GMCH Heatsink - Installed on Board



## 4.4 Environmental Reliability Requirements

The environmental reliability requirements for the reference thermal solution are shown in Table 3 and Table 4. These should be considered as general guidelines. Validation test plans should be defined by the user based on anticipated use conditions and resulting reliability requirements.

The ATX testing will be performed with the sample board mounted on a test fixture and includes a processor heatsink with a mass of 550g. The test profiles are unpackaged board level limits.

**Table 3. ATX Reference Thermal Solution Environmental Reliability Requirements (Board Level)**

Test <sup>1</sup>	Requirement	Pass/Fail Criteria <sup>2</sup>
Mechanical Shock	<ul style="list-style-type: none"> <li>• 3 drops for + and - directions in each of 3 perpendicular axes (i.e., total 18 drops).</li> <li>• Profile: 50 G, Trapezoidal waveform, 4.3 m/s [170 in/s] minimum velocity change</li> </ul>	Visual\Electrical Check
Random Vibration	<ul style="list-style-type: none"> <li>• Duration: 10 min/axis, 3 axes</li> <li>• Frequency Range: 5 Hz to 500 Hz</li> <li>• Power Spectral Density (PSD) Profile: 3.13 g RMS</li> </ul>	Visual/Electrical Check
Unbiased Humidity	<ul style="list-style-type: none"> <li>• 85 % relative humidity / 55 °C, 576 hours</li> </ul>	Visual Check

**NOTES:**

1. The above tests should be performed on a sample size of at least 12 assemblies from 3 different lots of material.
2. Additional Pass/Fail Criteria may be added at the discretion of the user.



**Table 4. Balanced Technology Extended (BTX) Reference Thermal Solution Environmental Reliability Requirements (System Level)**

Test <sup>1</sup>	Requirement	Pass/Fail Criteria <sup>2</sup>
Mechanical Shock <sup>5</sup>	<ul style="list-style-type: none"> <li>• 2 drops for + and - directions in each of 3 perpendicular axes (i.e., total 12 drops).</li> <li>• Profile: 25g, Trapezoidal waveform, 5.7 m/s [225 in/sec] minimum velocity change.</li> </ul>	Visual\Electrical Check
Random Vibration <sup>5</sup>	<ul style="list-style-type: none"> <li>• Duration: 10 min/axis, 3 axes</li> <li>• Frequency Range: .001 g<sup>2</sup>/Hz @ 5Hz, ramping to .01 g<sup>2</sup>/Hz @20 Hz, .01 g<sup>2</sup>/Hz @ 20 Hz to 500 Hz</li> <li>• Power Spectral Density (PSD) Profile: 2.20 g RMS</li> </ul>	Visual/Electrical Check
Power Cycling	<ul style="list-style-type: none"> <li>• 7500 cycles (on/off) of minimum temperature 27 °C / maximum temperature 96 °C</li> <li>• 1400 cycles (on/off) of minimum temperature 35 °C / maximum temperature 96 °C</li> <li>• A 15 second dwell at high / low temperature for both test cycles.</li> </ul>	Thermal Performance
Unbiased Humidity	<ul style="list-style-type: none"> <li>• 85 % relative humidity / 55 °C, 576 hours</li> </ul>	Visual Check

**NOTES:**

1. The above tests should be performed on a sample size of at least 12 assemblies from 3 different lots of material.
2. Additional Pass/Fail Criteria may be added at the discretion of the user.
3. Mechanical Shock minimum velocity change is based on a system weight of 20 to 29 lbs.
4. For the chassis level testing the system will include: 1 HD, 1 ODD, 1 PSU, 2 DIMMs and the I/O shield.
5. BTX reference solution testing for shock and vibration is to mount the sample board in a BTX chassis in with a thermal module assembly (TMA) having a maximum mass of 900g.



## Appendix A Enabled Suppliers

Enabled suppliers for the GMCH reference thermal solution are listed in Table 5 and Table 6. The supplier contact information is listed in Table 7.

**Note:** These vendors and devices are listed by Intel as a convenience to Intel's general customer base, but Intel does not make any representations or warranties whatsoever regarding quality, reliability, functionality, or compatibility of these devices. This list and/or these devices may be subject to change without notice.

**Table 5. ATX Intel Reference Heatsink Enabled Suppliers for Intel® G35 Express Chipset**

ATX Items	Intel PN	AVC	CCI	Foxconn	Wieson
Heatsink & TIM	D31682-001	S902Y10001	335I833301A	2Z802-032	
Plastic Clip	C85370-001	P109000024	334C863501A	3EE77-002	
Wire Clip	D29082-001	A208000233	334I833301A	3KS02-155	
Anchor	C85376-001			2Z802-015	G2100C888-143

**Table 6. Balanced Technology Extended (BTX) Intel® Reference Heatsink Enabled Suppliers for Intel® G35 Express Chipset**

BTX Items	Intel PN	AVC	CCI	Foxconn	Wieson
Heatsink assembly (HS/TIM & Wire Clip)	D34258-001	S905Y00001	00I833201A	2ZQ99-066	
Anchor (Lead Free)	A13494-008			HB9703E-DW	G2100C888-064H



Table 7. Supplier Contact Information

Supplier	Contacts	Phone	Email
AVC (Asia Vital Components)	David Chao	+886-2-2299-6930 ext. 7619	david_chao@avc.com.tw
	Raichel Hsu	+886-2-2299-6930 ext. 7630	raichel_hsi@avc.com.tw
CCI(Chaun Choung Technology)	Monica Chih	+886-2-2995-2666	monica_chih@ccic.com.tw
	Harry Lin	(714) 739-5797	hlinack@aol.com
Foxconn	Jack Chen	(408) 919-6121	jack.chen@foxconn.com
	Wanchi Chen	(408) 919-6135	wanchi.chen@foxconn.com
Wieson Technologies	Chary Lee	+886-2-2647-1896 ext. 6684	chary@wieson.com
	Henry Liu	+886-2-2647-1896 ext. 6330	henry@wieson.com

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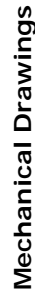
## Appendix B Mechanical Drawings

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The following table lists the mechanical drawings available in this document.

Drawing Name	Page Number
GMCH Package Drawing	29
GMCH Keep-Out Restrictions for ATX Platforms	31
GMCH Keep-Out Restrictions for Balanced Technology Extended (BTX) Platforms	32
GMCH Reference Heatsink for ATX Platforms – Sheet 1	33
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GMCH Reference Heatsink for Balanced Technology Extended (BTX) Platforms	39
GMCH Reference Heatsink for Balanced Technology Extended (BTX) Platforms – Clip	40

**NOTE:** Unless otherwise specified, all figures in this appendix are dimensioned in millimeters. Dimensions shown in brackets are in inches.



**Notes:**

2. DIE OUTLINE DOES NOT REPRESENT AN ACTUAL DIE AND IS DRAWN FOR REFERENCE ONLY. REFER TO INTEL REPRESENTATIVE FOR FROZEN DIE SIZE
3. THIS IS A CAPACITOR AREA, HANDLING KEEP OUT ZONE.
4. THIS IS A HANDLING AREA, PACKAGE KEEP OUT ZONE.
5. ALL DIMENSIONS UNLESS OTHERWISE SPECIFIED ARE IN MILLIMETER
6. FOR EXACT BGA LOCATIONS REFER TO INTEL REPRESENTATIVE FOR THE X,Y BALL COORDINATE SPREADSHEET

**TOP VIEW**

**SIDE VIEW (UNMOUNTED PKG)**

**BOTTOM VIEW PKG**

**DETAIL A**  
SCALE: X=1  
1226 Pieces

**DETAIL B**  
SCALE: 5:1

**DETAIL C**  
SCALE: 5:1

**DETAIL D**  
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**DETAIL E**  
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**DETAIL F**  
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SCALE: 5:1

**DETAIL**



Figure 12. GMCH Keep-Out Restrictions for ATX Platforms

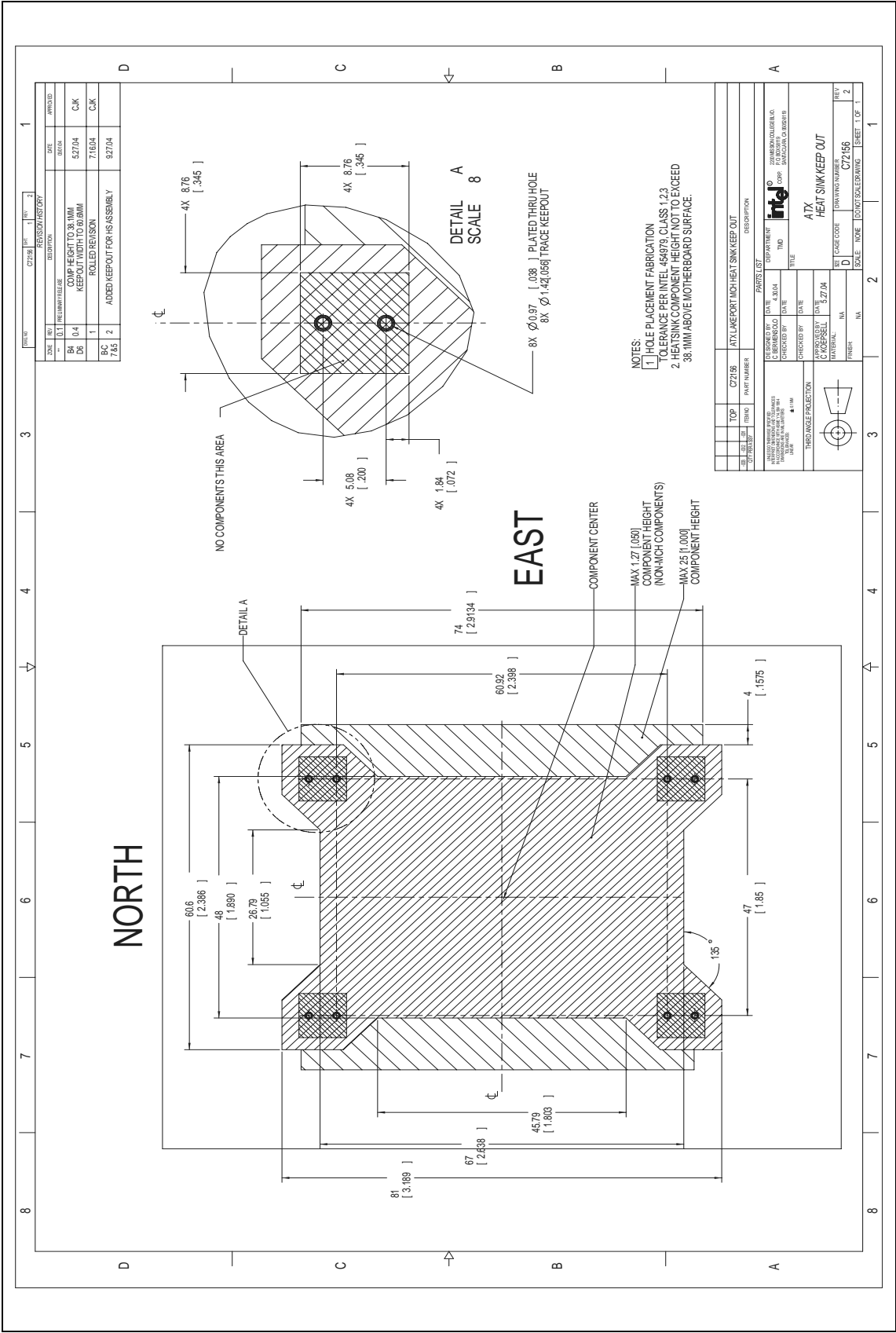




Figure 13. GMCH Keep-Out Restrictions for Balanced Technology Extended (BTX) Platforms

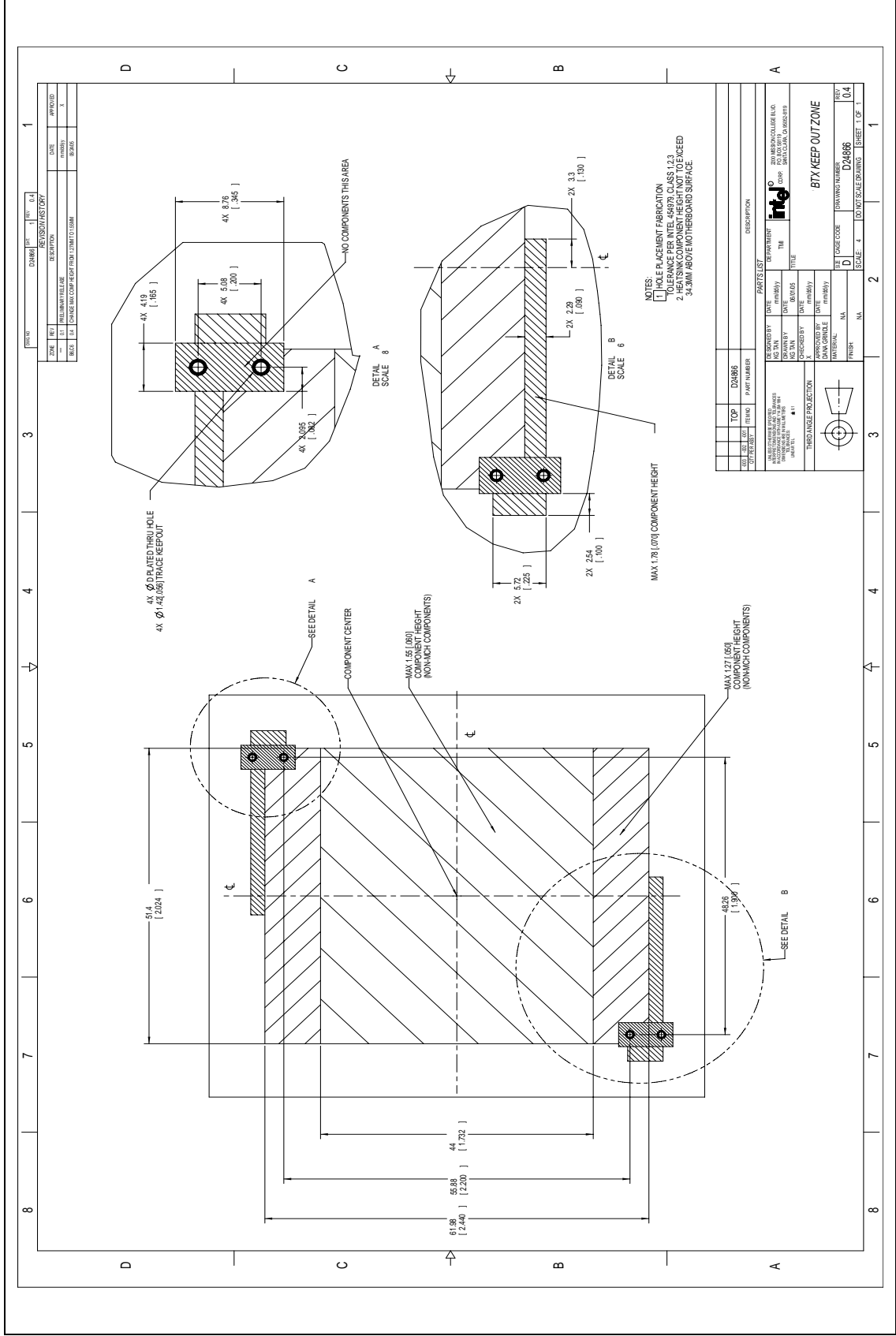
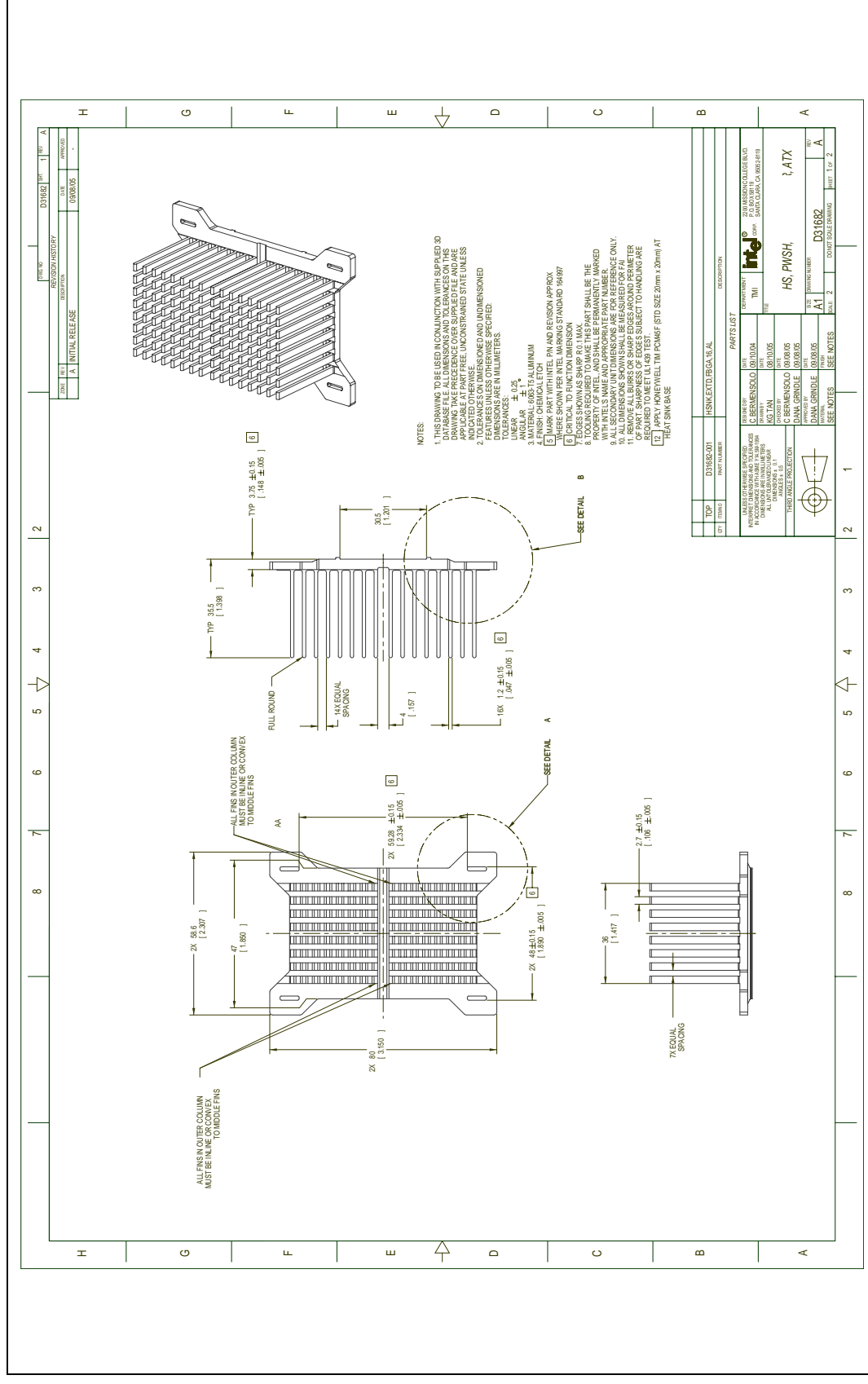
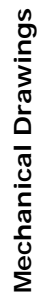




Figure 14. GMCH Reference Heatsink for ATX Platforms – Sheet 1



[illegible]



Mechanical Drawings

Figure 16. GMCH Heatsink for ATX Platforms – Anchor

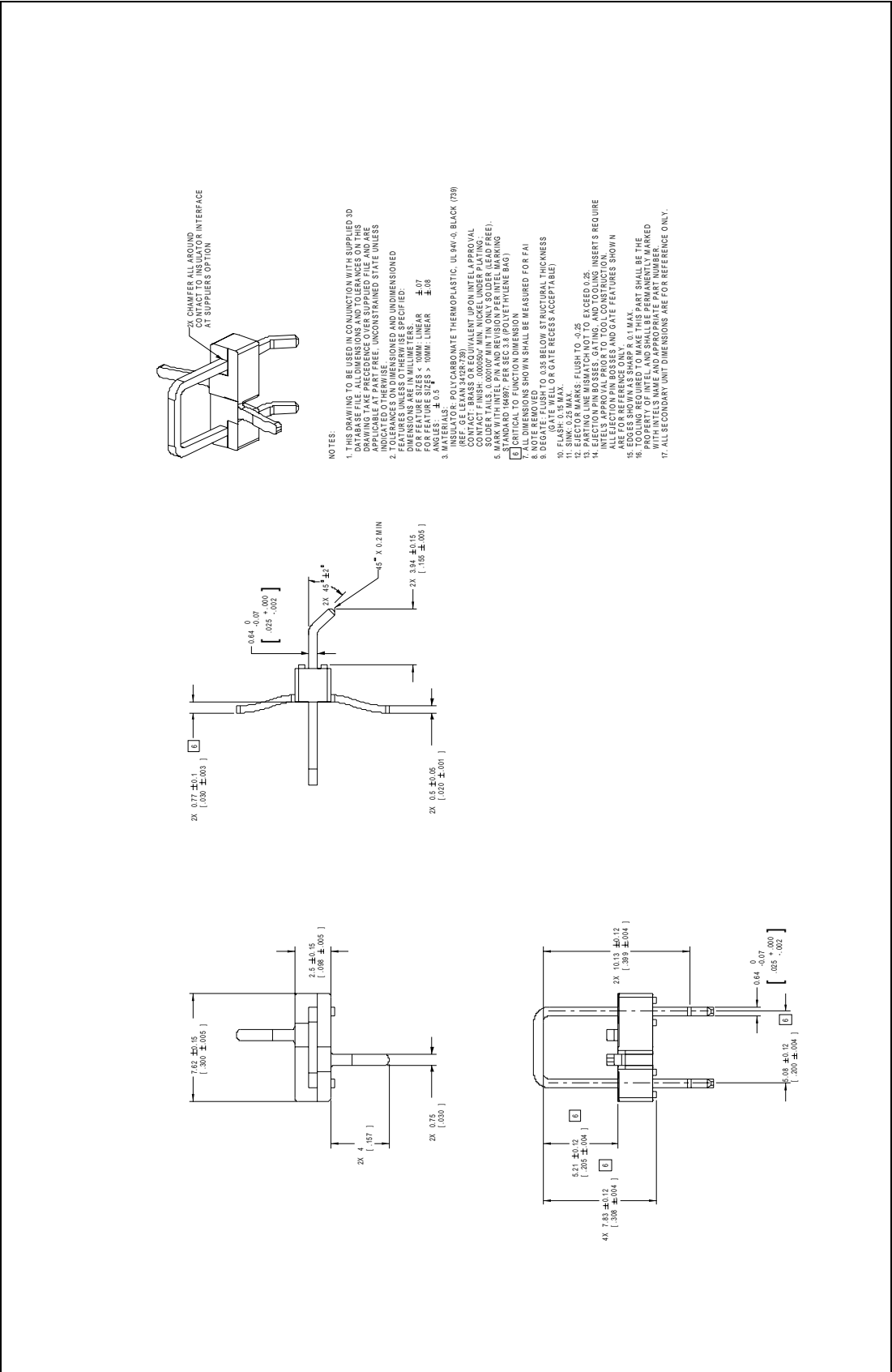
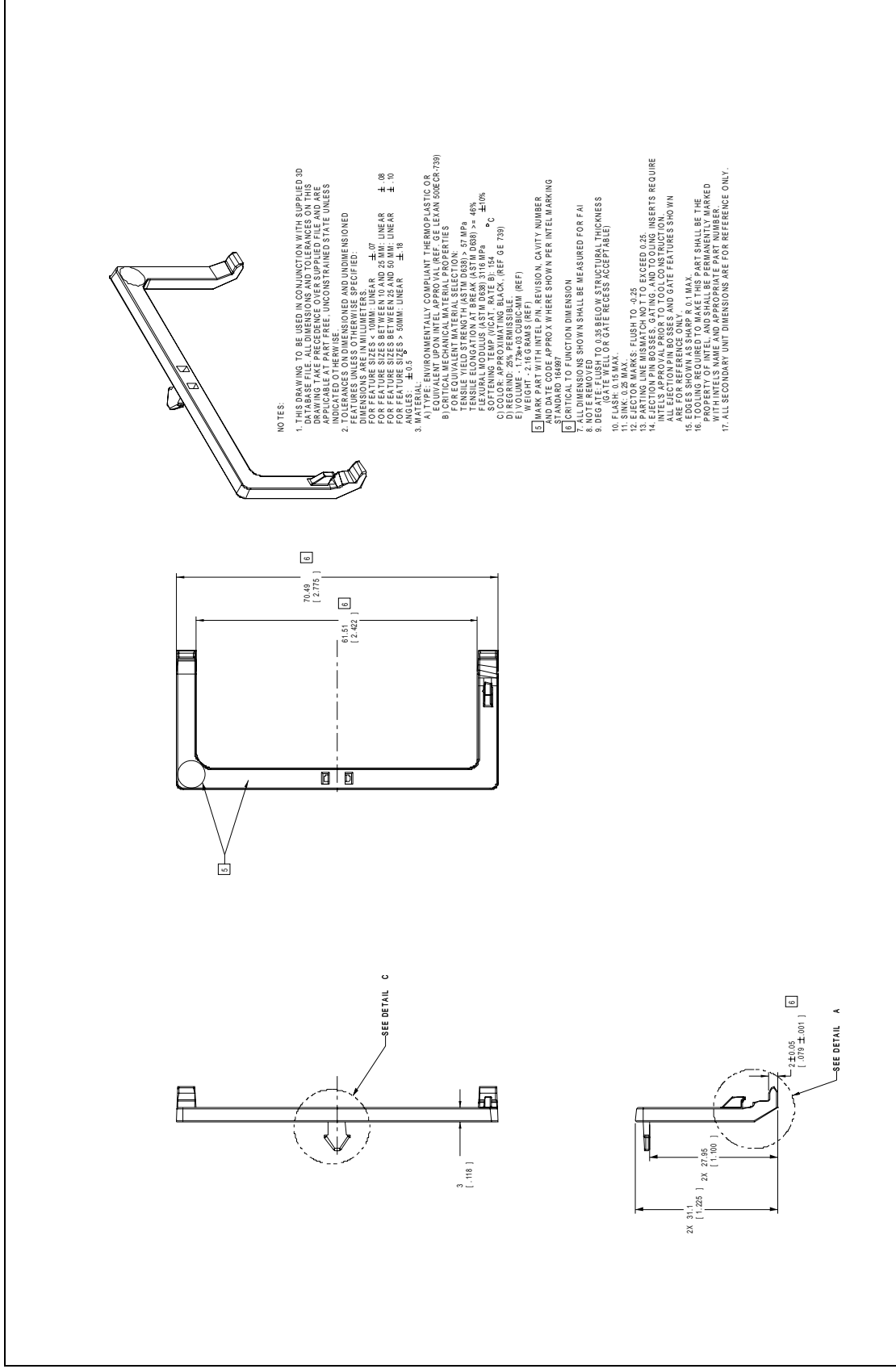




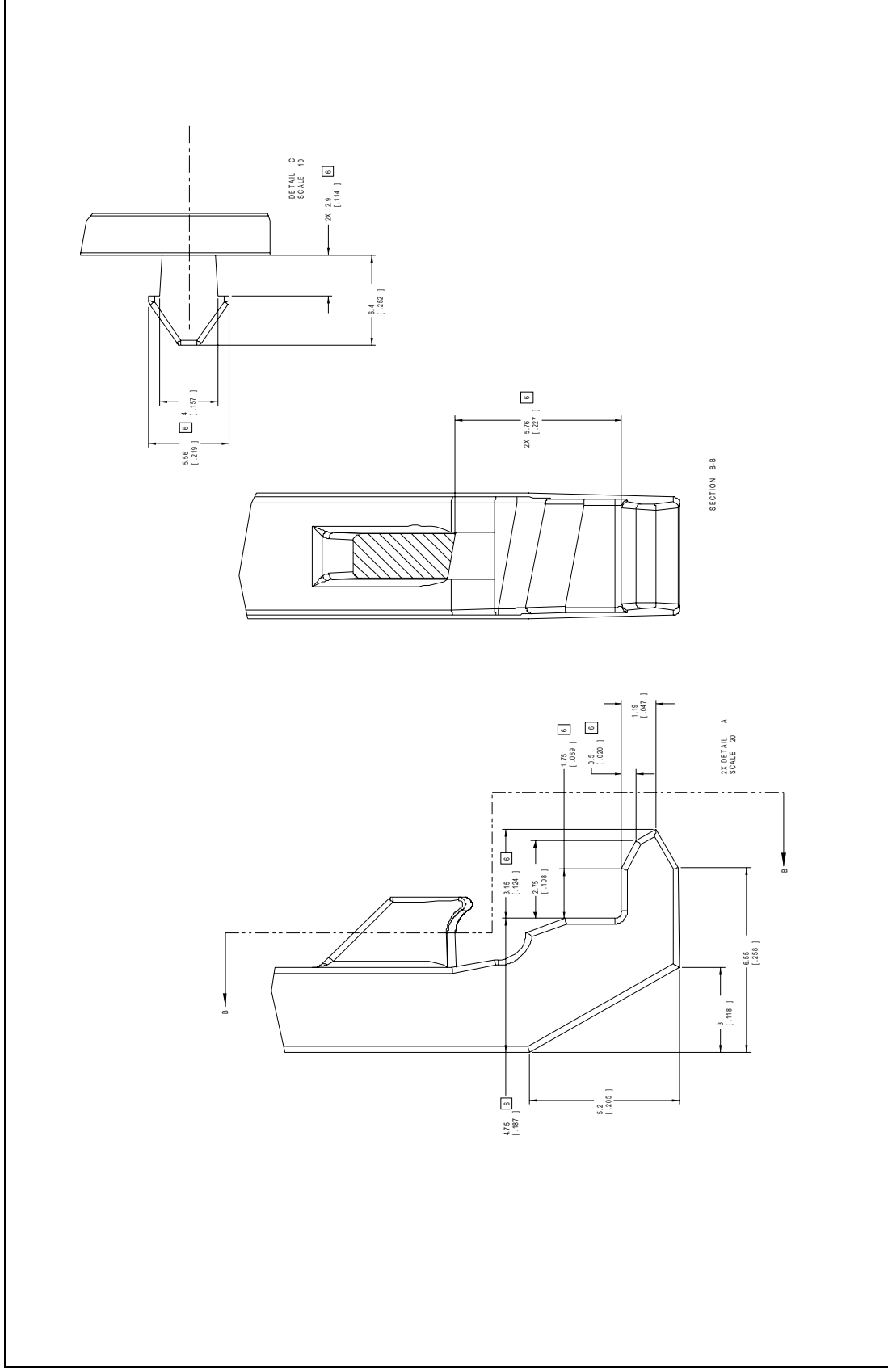
Figure 17. GMCH Reference Heatsink for ATX Platforms – Ramp Retainer Sheet 1

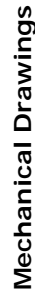




## Mechanical Drawings

Figure 18. GMCH Reference Heatsink for ATX Platforms – Ramp Retainer Sheet 2





**REVISION HISTORY**

REV	DATE	DESCRIPTION
1	09/09/05	INITIAL RELEASE

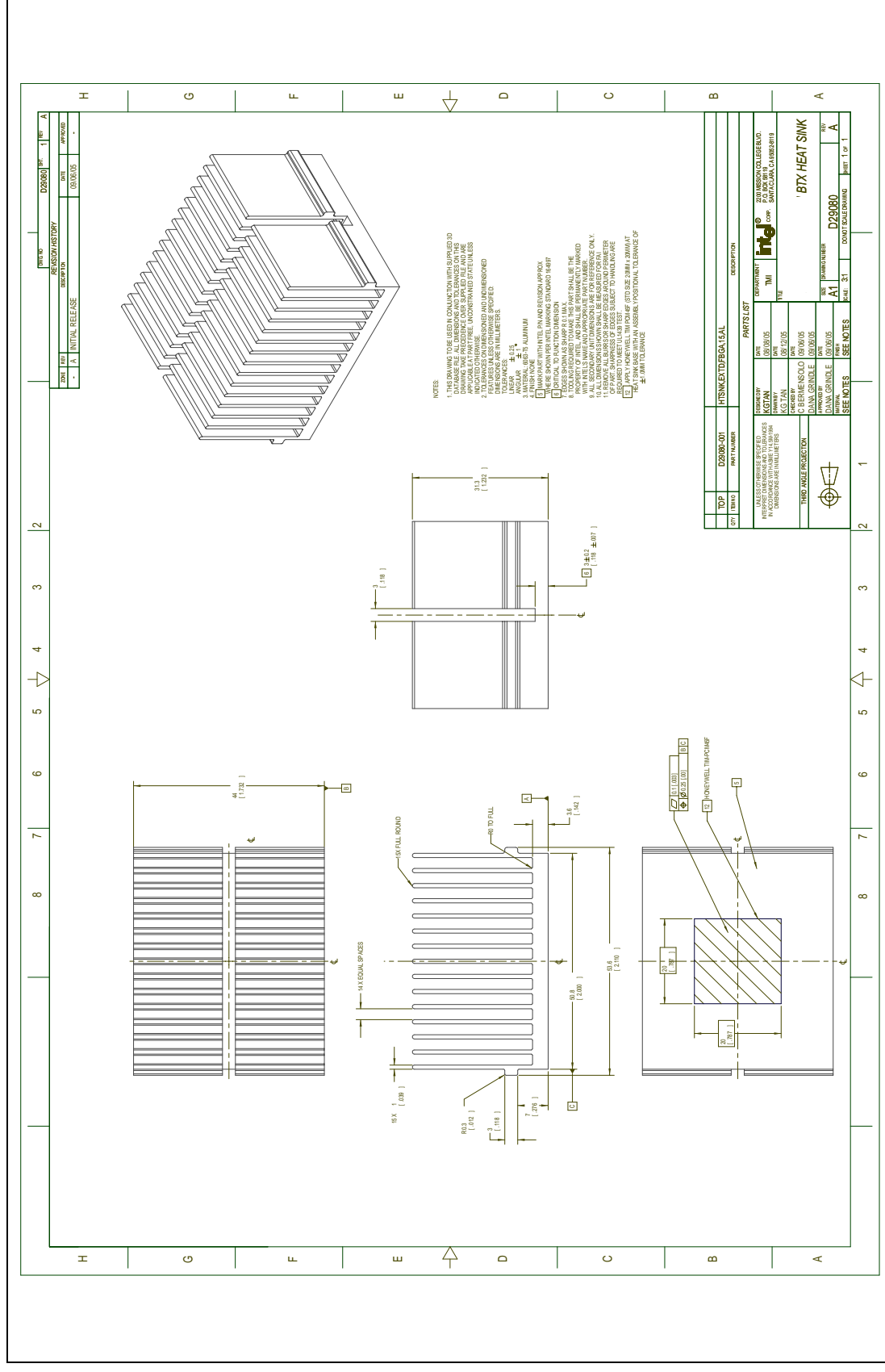
**PARTS LIST**

ITEM	DESCRIPTION	QTY
1	SPRING, HSS, 300 LBS, 65.0MM	1

**NOTES:**

- THIS DRAWING TO BE USED IN CONJUNCTION WITH SUPPLIED 3D INTERACTIVE FILE. ALL DIMENSIONS AND TOLERANCES ON THIS DRAWING TAKE PRECEDENCE OVER SUPPLIED FILE AND ARE APPLICABLE AT PART FREE, UNCONSTRAINED STATE UNLESS SPECIFIED OTHERWISE.
- TOLERANCES ON DIMENSIONS AND UNDIMENSIONED FEATURES, UNLESS OTHERWISE SPECIFIED:  
DIMENSIONS: LINEAR ±0.25  
ANGLES: ±3°
- TYPE: ASTM A228 MUSIC WIRE  
PLATING: ELECTROLESS NICKEL OR EQUIVALENT UPON INTEL APPROVAL
- STANDARD: MIL-STD-883C METHOD 2000
- MARKING: INTEL PART NUMBER AND DIMENSION PER INTEL MARKING STANDARD (64887 PER SEC 3.8 POLY(ETHYLENE BAG))
- REMOVE ALL SHARP EDGES AND BURRS ASSURED FOR FAULT TOLERANCE ANALYSIS
- ALL DIMENSIONS ARE FOR REFERENCE ONLY.

Figure 20. GMCH Reference Heatsink for Balanced Technology Extended (BTX) Platforms



[illegible]